

Answer on Question #44021 – Physics – Mechanics-Kinematics-Dynamics

the magnitude of two vectors \vec{p} and \vec{q} differ by 1. the magnitude of their resultant makes an angle of $\tan^{-1}(3/4)$ with \vec{p} . the angle between \vec{p} and \vec{q} is

Solution:

$\alpha = \arctan\left(\frac{3}{4}\right)$ – angle between vector \vec{p} and resultant vector;

β – angle between vector \vec{p} and vector \vec{q} ;

First vector:

$$\vec{p} = (p_x, p_y), \text{ magnitude: } P = \sqrt{p_x^2 + p_y^2}$$

Second vector:

$$\vec{q} = (q_x, q_y), \text{ magnitude: } Q = \sqrt{q_x^2 + q_y^2}$$

Let's make a substitution:

$$p_x q_x + p_y q_y = X$$

Difference between magnitude of two vectors:

$$\begin{aligned} P - Q &= 1 \\ Q &= P - 1 \quad (1) \end{aligned}$$

Resultant vector:

$$\begin{aligned} \vec{r} &= \vec{p} + \vec{q} \\ r &= (p_x + q_x, p_y + q_y) \end{aligned}$$

Scalar product of the first vector and resultant vector:

$$\begin{aligned} \vec{p} \cdot \vec{r} &= p_x(p_x + q_x) + p_y(p_y + q_y) = |\vec{p}| \cdot |\vec{r}| \cdot \cos \alpha = \\ &= P \cdot \sqrt{(p_x + q_x)^2 + (p_y + q_y)^2} \cdot \cos \alpha \\ p_x^2 + p_y^2 + p_x q_x + p_y q_y &= P \cdot \sqrt{(p_x + q_x)^2 + (p_y + q_y)^2} \cdot \cos \alpha \\ P^2 + X &= P \cdot \sqrt{(p_x + q_x)^2 + (p_y + q_y)^2} \cdot \cos \alpha = \\ &= P \sqrt{p_x^2 + 2p_x q_x + q_x^2 + p_y^2 + 2p_y q_y + q_y^2} \cdot \cos \alpha \\ &= P \sqrt{P^2 + Q^2 + 2X} \cdot \cos \alpha \end{aligned}$$

Scalar product of the first vector and second vector:

$$\begin{aligned} \vec{p} \cdot \vec{q} &= p_x q_x + p_y q_y = |\vec{p}| \cdot |\vec{q}| \cdot \cos \beta = \\ &= P \cdot Q \cdot \cos \beta \quad (3) \\ \cos \beta &= \frac{p_x q_x + p_y q_y}{P \cdot Q} = \frac{X}{P \cdot Q} \end{aligned}$$

Thus, we have system with three equations:

$$\begin{cases} Q = P - 1 & (1) \\ P^2 + X = P \sqrt{P^2 + Q^2 + 2X} \cdot \cos \alpha \\ \cos \beta = \frac{X}{P \cdot Q} \end{cases}$$

We have 3 equations and 4 unknown (P, Q, X and $\cos \beta$), hence we can't find $\cos \beta$ – cosine of angle between vector p and vector q.