

ANSWER on Question #81519 – Math – Differential Equations

QUESTION

Reduce the following PDE to a set of three ODEs by the method of separation of variables

$$\frac{1}{r} \frac{\partial}{\partial r} \left(r \cdot \left(\frac{\partial V}{\partial r} \right) \right) + \left(\frac{1}{r^2} \right) \cdot \frac{\partial^2 V}{\partial \theta^2} + \frac{\partial^2 V}{\partial z^2} + k^2 \cdot V = 0$$

SOLUTION

Assume

$$V(r, \theta, z) = R(r)\Theta(\theta)Z(z)$$

Then,

$$\Theta Z \frac{1}{r} \frac{\partial}{\partial r} \left(r \cdot \left(\frac{\partial R}{\partial r} \right) \right) + R Z \left(\frac{1}{r^2} \right) \cdot \frac{\partial^2 \Theta}{\partial \theta^2} + R \Theta \frac{\partial^2 Z}{\partial z^2} + k^2 \cdot R \Theta Z = 0 \left| \div \left(\frac{1}{R \Theta Z} \right) \rightarrow \right.$$

$$\frac{1}{R} \frac{1}{r} \frac{\partial}{\partial r} \left(r \cdot \left(\frac{\partial R}{\partial r} \right) \right) + \frac{1}{\Theta} \left(\frac{1}{r^2} \right) \cdot \frac{\partial^2 \Theta}{\partial \theta^2} + \frac{1}{Z} \frac{\partial^2 Z}{\partial z^2} + k^2 = 0 \rightarrow$$

$$\frac{1}{R} \frac{1}{r} \frac{\partial}{\partial r} \left(r \cdot \left(\frac{\partial R}{\partial r} \right) \right) + \frac{1}{\Theta} \left(\frac{1}{r^2} \right) \cdot \frac{\partial^2 \Theta}{\partial \theta^2} + k^2 = - \frac{1}{Z} \frac{\partial^2 Z}{\partial z^2}$$

In the above equation the left-hand side depends on r and θ , while the right-hand side depends on z . The only way these two members are going to be equal for all values of r , θ and z is when both of them are equal to a constant. Let us define such constant as $-l^2$.

With this choice for the constant, we obtain:

$$\frac{d^2 Z}{dz^2} - l^2 \cdot Z = 0$$

The general solution of this equation is:

$$Z(z) = A_1 e^{lz} + A_2 e^{-lz}$$

Such a solution, when considering the specific boundary conditions, will allow $Z(z)$ to go to zero for z going to $\pm\infty$, which makes physical sense. If we had given the constant a value of l^2 , we would have had periodic trigonometric functions, which do not tend to zero for z going to infinity.

Once sorted the z –dependency, we need take care of r and θ .

$$\frac{1}{R} \frac{1}{r} \frac{\partial}{\partial r} \left(r \cdot \left(\frac{\partial R}{\partial r} \right) \right) + \frac{1}{\Theta} \left(\frac{1}{r^2} \right) \cdot \frac{\partial^2 \Theta}{\partial \theta^2} + k^2 = -l^2 \rightarrow$$

$$\frac{1}{R} \frac{1}{r} \frac{\partial}{\partial r} \left(r \cdot \left(\frac{\partial R}{\partial r} \right) \right) + \frac{1}{\Theta} \left(\frac{1}{r^2} \right) \cdot \frac{\partial^2 \Theta}{\partial \theta^2} = -(k^2 + l^2) \rightarrow$$

$$\frac{1}{R} \frac{1}{r} \left(\frac{\partial R}{\partial r} + r \cdot \frac{\partial^2 R}{\partial r^2} \right) + \frac{1}{\Theta} \left(\frac{1}{r^2} \right) \cdot \frac{\partial^2 \Theta}{\partial \theta^2} = -(k^2 + l^2) \rightarrow$$

$$\frac{1}{R} \frac{\partial^2 R}{\partial r^2} + \frac{1}{R} \frac{1}{r} \frac{\partial R}{\partial r} + \frac{1}{\Theta} \left(\frac{1}{r^2} \right) \cdot \frac{\partial^2 \Theta}{\partial \theta^2} = -(k^2 + l^2) \Big| \times (r^2) \rightarrow$$

$$\frac{r^2}{R} \frac{\partial^2 R}{\partial r^2} + \frac{r}{R} \frac{\partial R}{\partial r} + (k^2 + l^2)r^2 = \frac{1}{\Theta} \cdot \frac{\partial^2 \Theta}{\partial \theta^2}$$

Again we are in a situation where the only way a solution can be found for the above equation is when both members are equal to a constant. This time we select a positive constant, which we call m^2 . The equation for Θ becomes, for:

$$\frac{d^2 \Theta}{d\theta^2} + m^2 \Theta = 0$$

This solution is well suited, to describe the variation for an angular coordinate like θ . Had we chosen the set both members equal to a negative number, we would have ended up with exponential functions with a different value assigned to $\Theta(\theta)$ for each 360° turn, a clear non-physical solution.

Last to be examined is the r –dependency. We have:

$$\frac{r^2}{R} \frac{d^2 R}{dr^2} + \frac{r}{R} \frac{dR}{dr} + (k^2 + l^2)r^2 = m^2 \rightarrow$$

$$r^2 \cdot \frac{d^2 R}{dr^2} + r \cdot \frac{dR}{dr} + [(k^2 + l^2)r^2 - m^2] \cdot R = 0$$

This equation is a well-known equation of mathematical physics called parametric Bessel's equation. With simple linear transformation of variable, $x = r \cdot \sqrt{(k^2 + l^2)}$, equation is readily changed into a Bessel's equation:

$$\frac{dR}{dr} = \frac{dR}{dx} \cdot \frac{dx}{dr} = \sqrt{k^2 + l^2} \cdot R'$$

$$\frac{d^2R}{dr^2} = \frac{d}{dx} \left(\sqrt{k^2 + l^2} \cdot R' \right) \cdot \frac{dx}{dr} = (k^2 + l^2) \cdot R''$$

Then,

$$r^2 \cdot \frac{d^2R}{dr^2} + r \cdot \frac{dR}{dr} + [(k^2 + l^2)r^2 - m^2] \cdot R = 0 \rightarrow$$

$$\frac{x^2}{(k^2 + l^2)} \cdot (k^2 + l^2) \cdot R'' + \frac{x}{\sqrt{k^2 + l^2}} \cdot \sqrt{k^2 + l^2} \cdot R' + [x^2 - m^2] \cdot R = 0 \rightarrow$$

$$x^2 \cdot R'' + x \cdot R' + [x^2 - m^2] \cdot R = 0$$

where R'' and R' indicate the first and second derivatives with respect to x .

In what follows we will assume that m is a real, non-negative number.

Linearly independent solutions are typically denote $J_m(x)$ (Bessel Functions) and $N_m(x)$ (Neumann Functions).

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