

## Answer on Question #76736 – Math – Quantitative Methods

### Question

Apply Runge Kutta Method to solve an I.V.P. complicated problem.

### Solution

The motion of a material point of mass  $m$  under the action of external forces is described by Newton's second law. Let the point move along the  $x$  axis, then the function  $x(t)$  is the position of the point at time  $t$ , it satisfies the ordinary differential equation of the second order  $mx'' = F(t, x, x')$ . For example, balance of forces for damped harmonic oscillators:

$$x'' + 2x' + 10x = 0, \quad x(0) = 2, \quad x'(0) = 5$$

The exact solution:

$$x(t) = e^{-t} \left( \frac{7}{3} \sin(3t) + 2 \cos(3t) \right)$$

For a numerical solution, we transform the second-order differential equation into a system of first-order differential equations by means of the change of variables:

$$\begin{cases} y_0(t) = x(t), & y_1(t) = x'(t) \\ y_0'(t) = x'(t) = y_1(t) \\ y_1'(t) = x''(t) = -2 \cdot y_1(t) - 10 \cdot y_0(t), \end{cases} \quad x(0) = y_0(0) = 2, \quad x'(0) = y_1(0) = 5$$

Approximations calculated using the Runge-Kutta method of order 4. For this method, each step requires the use of the following four values ( $h$ -step size):

$$\begin{aligned} k_1 &= h \cdot f(t_n, y_n) \\ k_2 &= h \cdot f\left(t_n + \frac{1}{2}h, y_n + \frac{1}{2}k_1\right) \\ k_3 &= h \cdot f\left(t_n + \frac{1}{2}h, y_n + \frac{1}{2}k_2\right) \\ k_4 &= h \cdot f(t_n + h, y_n + k_3) \end{aligned}$$

Then we calculate the approximation to the solution:

$$y_{n+1} = y_n + \frac{1}{6}(k_1 + 2k_2 + 2k_3 + k_4)$$

For the system of equations:

$$\begin{cases} y_{n+1}^0 = y_n^0 + \frac{1}{6}(k_1^0 + 2k_2^0 + 2k_3^0 + k_4^0) \\ y_{n+1}^1 = y_n^1 + \frac{1}{6}(k_1^1 + 2k_2^1 + 2k_3^1 + k_4^1) \end{cases},$$

$$k_1^0 = h \cdot y_n^1$$

$$k_2^0 = h \cdot \left( y_n^1 + \frac{1}{2} k_1^1 \right)$$

$$k_3^0 = h \cdot \left( y_n^1 + \frac{1}{2} k_2^1 \right)$$

$$k_4^0 = h \cdot (y_n^1 + k_3^1)$$

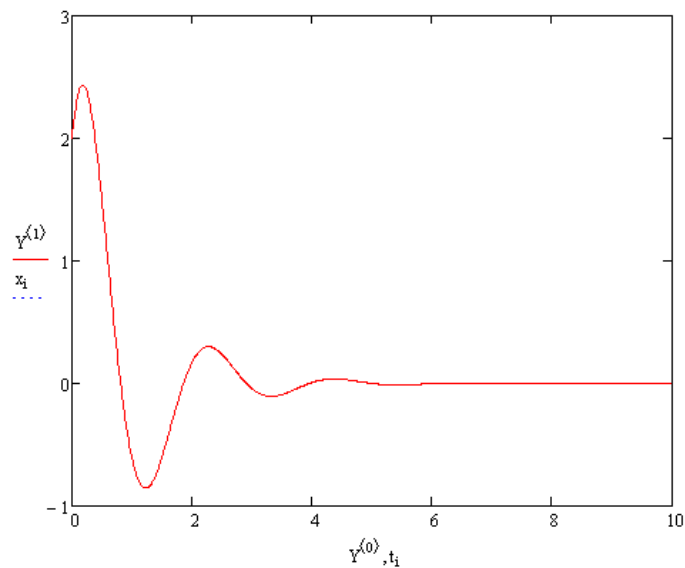
$$k_1^1 = h \cdot (-2 \cdot y_n^1 - 10 \cdot y_n^0)$$

$$k_2^1 = h \cdot \left( -2 \cdot \left( y_n^1 + \frac{1}{2} k_1^1 \right) - 10 \cdot \left( y_n^0 + \frac{1}{2} k_1^0 \right) \right)$$

$$k_3^1 = h \cdot \left( -2 \cdot \left( y_n^1 + \frac{1}{2} k_2^1 \right) - 10 \cdot \left( y_n^0 + \frac{1}{2} k_2^0 \right) \right)$$

$$k_4^1 = h \cdot (-2 \cdot (y_n^1 + k_3^1) - 10 \cdot (y_n^0 + k_3^0))$$

Exact ( $x_i$ ) and approximate ( $Y$ ) solutions ( $h=0.01$ ):



The difference of solutions:

