Answer on Question #42801 - Math - Linear Algebra

To translate an object by a vector \mathbf{v} , each homogeneous vector $\mathbf{p} = \begin{bmatrix} p_x \\ p_y \\ p_z \\ 1 \end{bmatrix}$ can be multiplied by this

translation matrix:

$$T_{\mathbf{v}} = \begin{bmatrix} 1 & 0 & 0 & v_x \\ 0 & 1 & 0 & v_y \\ 0 & 0 & 1 & v_z \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

As shown below, the multiplication will give the expected result:

$$T_{\mathbf{v}}\mathbf{p} = egin{bmatrix} 1 & 0 & 0 & v_x \ 0 & 1 & 0 & v_y \ 0 & 0 & 1 & v_z \ 0 & 0 & 0 & 1 \end{bmatrix} egin{bmatrix} p_x \ p_y \ p_z \ 1 \end{bmatrix} = egin{bmatrix} p_x + v_x \ p_y + v_y \ p_z + v_z \ 1 \end{bmatrix} = \mathbf{p} + \mathbf{v}$$